

## US005555503A

# United States Patent [19]

# Kyrtsos et al.

[11] Patent Number:

5,555,503

[45] Date of Patent:

Sep. 10, 1996

[54]	SYSTEM AND METHOD FOR PROVIDING
	ACCURATE VEHICLE POSITIONING USING
	SPATIAL BIAS TECHNIQUES

- [75] Inventors: Christos T. Kyrtsos, Peoria; Adam J. Gudat, Edelstein; Dana A. Christensen, Peoria; Douglas W. Friedrich, Pekin; Darrell E. Stafford, Dunlap, all of Ill.
- [73] Assignee: Caterpillar Inc., Peoria, Ill.
- [21] Appl. No.: 155,374
- [22] Filed: Nov. 23, 1993

### Related U.S. Application Data

[63]	Continuation of Ser. No. 628,560, Dec. 3, 1990, abandoned,
	and a continuation of Ser. No. 487,980, filed as PCT/US89/
	05580 Dec. 11, 1989.

[31]	Int. CL	GUOF 105/UU
[52]	U.S. Cl	364/449; 364/460; 342/357;
		342/457
[58]	Field of Search	364/440 453

#### [56] References Cited

## U.S. PATENT DOCUMENTS

3,630,079	12/1971	Hughes 73/178
_,	11/1973	
3,769,710		Reister 33/320
4,114,155	9/1978	Raab 343/105 R
4,445,118	4/1984	Taylor et al 343/357
4,485,383	11/1984	Maher 343/352
4,578,678	2/1986	Melocik et al 342/357
4,599,620	3/1986	Evans 342/357
4,646,096	2/1987	Fotheringham 343/357
4,647,784	3/1987	Stephens 250/501
4,652,884	3/1987	Starker 342/357
4,667,203	5/1987	Counselman, III 342/357
4,709,195	11/1987	Hellekson et al 318/254
4,713,767	12/1987	Sato et al 364/453
4,743,913	5/1988	Takai 342/457
4,751,512	6/1988	Longaker 342/357
4,785,463	11/1988	Janc et al 375/1

4,786,164	11/1988	Kawata 356/4
4,809,178	2/1989	Ninomiya et al 364/443
4,814,711	3/1989	Olsen et al 342/357
4,818,171	4/1989	Burholder 414/497
4,821,294	4/1989	Thomas 375/96
4,837,700	6/1989	Ando et al 364/449
4,839,835	6/1989	Hagenbuch 364/567
4,849,731	7/1989	Melocik 340/435
4,866,450	9/1989	Chisholm 342/410
4,870,422	9/1989	Counselman, III 342/357
4,876,659	10/1989	Devereux et al 364/717
4,894,655	1/1990	Joguet et al 340/988
4,899,285	2/1990	Nakayama et al 364/453
4,903,211	2/1990	Ando 364/443
4,903,212	2/1990	Yokouchi et al 364/449
4,918,609	4/1990	Yamawaki 364/449
4,924,699	5/1990	Kuroda et al 73/178 R
5,101,356	3/1992	Timothy et al 364/449

## FOREIGN PATENT DOCUMENTS

0181012	5/1986	Evenness Det Off
		European Pat. Off
0309293A2	3/1989	European Pat. Off
2554612	5/1985	France.
3310111	9/1984	Germany.
3538908A1	5/1987	Germany.
3912353A1	11/1989	Germany .
2126040	1/1987	United Kingdom .
WO87/07056	11/1987	WIPO.

#### OTHER PUBLICATIONS

J. Crowley, "Part 3: Knowledge Based Supervision of Robotics Systems," 1989 IEEE Conference on Robotics and Automation, 1989 pp. 37-42.

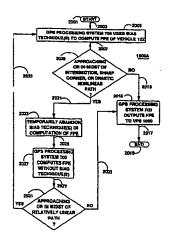
(List continued on next page.)

Primary Examiner—Collin W. Park Attorney, Agent, or Firm—Sterne, Kessler, Goldstein & Fox

#### [57] ABSTRACT

A vehicle position determination system and method provide accurate vehicle positioning using a global positioning system. Spatial bias techniques are used to improve positioning accuracy while the vehicle is in the midst of a relatively linear path and is not approaching a drastically nonlinear path. The use of spatial bias techniques is suspended while the vehicle is approaching or in a drastically nonlinear path.

## 17 Claims, 93 Drawing Sheets



#### OTHER PUBLICATIONS

Navstar GPS Space Segment/Navigation User Interface, Rockwell International Corporation, Nov. 30, 1987.

G. Geier et al., "Design of an Integrated Navigation System for Robotic Vehicle Application," *Journal of the Institute of Navigation*, Winter 1987-1988 pp. 325-336.

C. McGillem et al., "Infra-red Location System for Navigation of Autonomous Vehicles," *IEEE*, 1988 pp. 1236-1238.

IEEE Plans '86 Position Location and Navigation Symposium, Nov. 1986, S. Bose: "GPS/PLRS aided inertial land navigation system performance", pp. 496-504.

IEEE Proceedings, vol. 77, No. 11, Nov. 11, 1989. L. Schuchman et al.: "Applicability of an augmentated GPS for navigation in the National Airspace system", pp. 1709–1727, 1713, 1717, FIGS. 1–8.

Proceedings of 1988 IEEE International Conference on Robotics&Automation, vol. 2, Apr. 24–29, 1988, Philadelphia, IEEE Computer Soc. Press (Washington DC), L. E. Banta: "A self tuning navigation algorithm", pp. 1313–1314. IEEE Journal of Robotic&Automation, vol. 4, No. 3, Jun. 1988, IEEE (New York), C. Isik et al. "Pilot Level of a Hierarchical Controller for an Unmanned Mobile Robot", pp. 241–255.

Proceedings 1987 IEEE International Conference on Robotic&Automation, Mar. 31-Apr. 3, 1987 (Raleigh, NC), sponsored by IEEE Council on Robotic&Automation, vol. 3, D. McMenthon, "A zero-bank algorithm for Inverse Perspective of a Road fr Single Image", pp. 1444-1449.

IEEE Transactions on Pattern Analysis, vol. 10, No. 5 Sep. 1988, IEEE (New York), D. Kuan et al, "Autonomous robotic veh road following"pp. 648-658.

Proceedings 1987 IEEE Conference Mar. 31-Apr. 3, 1987, vol. 2, L. Conway et al.: "Tele-autonomous systems: Methods&Architectures for Intermingling autonomous & Telerobotic Technology" pp. 1121-1130.

Proceeding PR'88, The Computer Society Conference on Computer Vision&Pattern Recognition, Jun. 5-Sep. 1988 (Ann Arobr) S. Dickison et al., "An expert vision syste for Autonomous Land Vehicle Road Following", pp. 826-831. IEEE Journal of Robotics & Automation, vol. 4, No. 4, Aug. 1988, IEEE (New York) J. LeM "Domain-dependent reasoning for visual navigation of roadways", pp. 419-427 (Nissan) Mar. 24, 1988.

Wescon/87 Conference Record, vol. 31, 1987, (Los Angeles, US) M. T. Allison et al "The next generation navigation system", pp. 941–947.

IEEE Communications Magazine, vol. 26, No. 7, Jul. 1988 (New York) P. Enge et al. "Differential operation of global positioning system" pp. 48-59.

Patent Abstract of Japan, vol. 13, No. 306 (p. 897) Jul. 13, 1989 & JPA 1079679 (Toyota) Mar. 24, 1989.

Patent Abstract of Japan, vol. 12, No. 290 (p. 742) Aug. 9, 1988 & JPA 63066479 (Nissan) Mar. 24, 1988.

Randolph Hartman, "Integrated Laser Inertial/GPS Navigation (GPIRS)," Publication of Honeywell Inc., Feb., 1990, from a presentation at the Royal Institute of Navigation NAV '89 Satellite Navigation Conference, Oct., 1989.

GPS-90 Tutorials, The Institute of Navigation, Sep. 17-18, 1990, pp. 1-28.

P. Sheth et al., "A Generalized Symbolic Notation for Mechanism," *Transactions of the ASME*, Feb. 1971 pp. 102-112.

A. Brockstein, "GPS-Kalman-Augmented Inertial Navigation System Performance," *Naecom '76 Record*, 1976 pp. 864-871.

E. Martin, "Aiding GPS Navigation Functions," *Naecom '76 Record*, 1976 pp. 849–856.

Robotech Laboratory Company, no date.

T. Jacob, Integrated Navigation System for Approach Guidance for Regional Air-Traffic Using GPS, no date, pp. 176-187.

W. Sorenson, "Least-Squares estimation: From Gauss to Kalman," *IEEE Spectrum*, Jul. 1970 pp. 63-68.

C. Johnson, "In-Flight Transfer Alignment/Calibration of a Strapdown INS that Employs Carouseled Instruments and IMV Indexing," no date, pp. 1572-1573.

B. Culshaw et al., "Fibre Optic Gyroscopes In Inertial Navigation," no date.

K. Brodie et al., *Performance Analysis of Integrated Navigation Systems*, computer applications software technology, no date, pp. 605-690.

R. Brown, Random Signal Analysis & Kalman Filtering, Chapter 5, pp. 181-209, (no date).

Jorgensen, "18-Satellite Constellations," pp. 9-12, 1980.

C. Mueller et al., "Laser Gyro Land Navigation System Performance Predictions and Field Results," *IEEE*, 1984 pp. 81-89.

W. Euler, et al., "A Perspective on Civil Use of GPS," The Institute of Navigation, 36th Annual Meeting, 1980 pp. 1-7. H. Sakai, "Theoretical and Experimental Studies on the Dynamic Properties of Tyres Part I: Review of Theories of Rubber Friction," *International Journal of Vehicle Design*, 1981 pp. 78-110.

H. Sakai, "Theoretical and Experimental Studies on the Dynamic Properties of Tyres, Part II: Experimental Investigation of Rubber Friction and Deformation of a Tyre," International Journal of Vehicle Design, 1981 pp. 182–226. S. Divakaruni et al., "Fast Reaction and High Reliability of Strapdown Navigation Systems Using Ring Laser Gyros," IEEE 1984 pp. 315–322.

W. Auch, "Fibre Optic Gyroscope," 1984.

J. Ashjaee et al., "Precise Positioning Using a 4-Channel C/A Code GPS Receiver," IEEE 1984 pp. 236-244.

B. Parkinson et al., "Navstar: Global Positioning System— Ten Years Later," *Proceedings of the IEEE*, 1983 pp. 1178-1186.

M. Kuritsky et al., "Inertial Navigation," Proceedings of the IEEE, Oct. 1983 pp. 1156-1176.

R. Brown, Kalman Filtering Study Guide—A Guided Tour, 1984 pp. 1-19.

M. Kao et al., "Multiconfiguration Kalman Filter Design for High-Performance GPS Navigation," *IEEE Transactions on Automatic Control*, Mar. 1983 pp. 304-314.

H. Schwartz, "Sensitivity Analysis of an Integrated Navstar GPS/INS Navigation System to Component Failure," *Journal of the Institute of Navigation*, 1983 pp. 325-330.

"New Airbuses to Use Laser Inertial Reference Systems for Navigation," Litton Systems, Aircraft Engineering, Jun. 1983 pp. 10-11.

R. Greenspan et al., "Accuracy of Relative Positioning by Interferometry with Reconstructed Carrier GPS: Experimental Results," Third International Symposium on Satellite Doppler Positioning, Feb. 1982 pp. 1-19.

T. Upadhyay et al., "Benefits of Integrating GPS and Inertial Navigation," Jun. 1982 (pp. 1-13).

- F. Daum et al., "Decoupled Kalman Filters for Phased Array Radar Tracking," *IEEE Transactions on Automatic Control*, Mar. 1983 pp. 269–283.
- H. Sakai, "Theoretical and Experimental Studies on the Dynamic Properties of Tyres, Part III: Calculation of the Six Components of Force and Moment of a Tyre," *International Journal of Vehicle Design*, 1981 pp. 335-372.
- J. Sennott, "Real-Time GPS and Loran-C Dynamical Performance for Critical Marine Applications," *IEEE*, 1981 pp. 1006–1009.
- J. Sennott et al., "A Queueing Model for Analysis of a Bursty Multiple–Access Communication Channel," *IEEE*, 1981 pp. 317–321.
- J. Nielson et al., "GPS Aided Inertial Navigation," IEEE AES Magazine, Mar. 1986 pp. 20-26.
- H. Nii, "Blackboard Systems: The Blackboard Model Problem-solving and the Evolution of Blackboard Architectures," *The AI Magazine*, Summer 1986 pp. 38-53.
  H. Nii, "Blackboard Application Systems, Blackboard Systems, Blackboar
- H. Nii, "Blackboard Application Systems, Blackboard Systems from a Knowledge Engineering Perspective," *The Al Magazine*, Aug. 1986 pp. 82-89.
- Magazine, Aug. 1986 pp. 82-89. R. Cox et al., "Design for Maintainability: Litton's New Family of RLG Inertial Navigation Systems," *IEEE*, 1986 pp. 1115-1119.
- S. Divakaruni et al., "Ring Laser Gyro Inertial and GPS Integrated Navigation System for Commercial Aviation," *IEEE*, 1986 pp. 73–80.

- M. Grewal et al., "Application of Kalman Filtering to the Calibration and Alignment of Inertial Navigation Systems," *IEEE*, 1986 pp. 69–72.
- J. Raol et al., "On the Orbit Determination Problem," *IEEE Transactions on Aerospace and Electronic Systems*, May 1985 pp. 274–290.
- E. Udd, "Fiberoptic vs. Ring Laser Gyros: An Assessment of the Technology," *Laser Focus/Electro-Optics*, Dec. 1985 pp. 64-74.
- R. Majure et al., "Comparison of Laser Gyro IMU Configurations for Reentry Systems," *IEEE* 1986 pp. 96-100.
- Vehicle Dynamics Terminology, SAE J670e, 1984.
- E. Lerner, "Gyros in Business Aircraft," Aerospace America, Oct. 1984 pp. 66-69.
- J. Vaurus, "A Simulation of an Imbedded Software System for Global Positioning System Navigation," *Proceedings of the 1985 Winter Simulation Conference*, 1985 pp. 586-590.
- R. Dork, "Satellite Navigation Systems for Land Vehicles," *IEEE AES Magazine*, 1987 pp. 2-5.
- J. Sennott et al., Study of Differential Processing and Kalman Filtering of Bay Saint Louis Test Data, 1987 pp. 1-5.
- J. Collins, "GPS Equipment Survey, GPS—What does it all mean?," P.O.B., Jun.-Jul 1987 pp. 12-22.

